

DIGITAL DC DRIVE
DC 4Q 165AM DC 4Q 165A
MENU LEVELM MENU LEVEL
DIAGNOSTICSA MENU LEVEL
CONFIGURE DRIVEM CONFIGURE DRIVE
CONFIGURE ENABLE

▼ NOM MOTOR VOLTS

▼ ARMATURE CURRENT

▼ FIELD CURRENT

▼ FLD. CTRL MODE

▼ FLD. VOLTS RATIO

▼ CUR. LIMIT/SCALER

▼ AUTOTUNE

▼ SPEED FBK SELECT

▼ ENCODER LINES

▼ ENCODER RPM

▼ ENCODER SIGN

▼ SPD. INT TIME

▼ SPD. PROP GAIN

This is the power-up welcome screen
刚上电时显示Press the M key to get to MENU LEVEL
按M键进入菜单Press M. You are in MENU LEVEL, at DIAGNOSTICS
再按M键，进入“诊断”Up arrow to get to CONFIGURE DRIVE menu
“上”进入设备配置设定菜单Press M and up arrow to ENABLE drive configuration
All 7 LEDs blink in Configuration mode. Press E when done
按M和“上”，将可配置设为有效(7个灯开始闪)，然后按“E”Using the Up & Down arrows, enter rated motor voltage
设定电机电枢电压

Enter rated motor armature current 设定电机电枢电流

Enter rated field current. Skip if field is in Voltage mode
设定电机励磁电流Toggle between voltage and current modes
设定电机励磁控制方式In voltage mode: Ratio = (field volts/AC supply)*100
Example: For a 300V field and 460V supply, Ratio = 300/460*100 = 65%
如为电压方式，比值 例：励磁300V/电源460V =65%

Enter desired current limit setting. Usually 100% 电流限制

Leave this OFF. Autotune after calibration is complete 自整定

Choose from Armature Volts/Analog Tach/Encoder
速度反馈选择

Enter the pulses per rev. rating of the encoder 编码器的线数

Enter the max speed here. Corresponds to 100% speed
编码器最大转速Change the polarity of the encoder signal
编码器极性(正/负)

Speed loop integral gain 速度环积分时间

Speed loop proportional gain 速度环比例

- Set CONFIGURE ENABLE to DISABLE. The drive will display "CALIBRATING"
- Under MENU LEVEL/PARAMETER SAVE, press the M and UP to save your settings
再将可配置设为无效，最后保存参数。